Modal Logic: Logics of Knowledge and Belief

Eric Pacuit, University of Maryland

November 15, 2023

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- $K_a P \vee K_a \neg P$: "Ann knows whether P is true"
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 - $K_a K_a P$: "Ann knows that she knows that P"

Suppose there are three cards: 1, 2 and 3.

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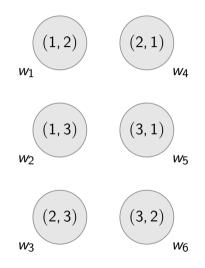
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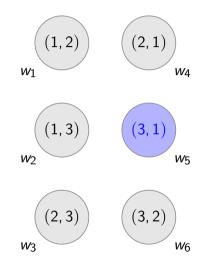
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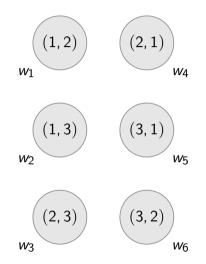
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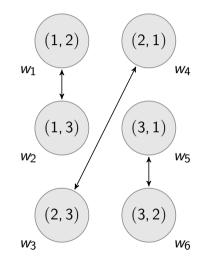
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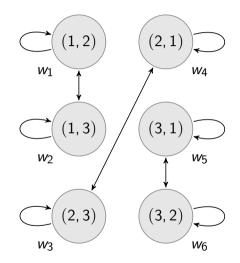
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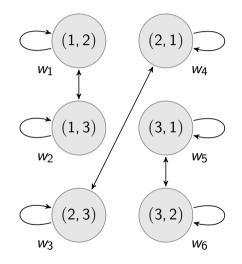
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Suppose H_i is intended to mean "Ann has card *i*"

 T_i is intended to mean "card *i* is on the table"

Eg.,
$$V(H_1) = \{w_1, w_2\}$$



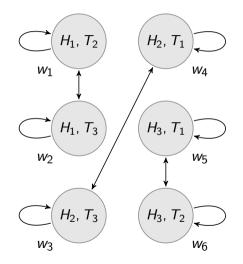
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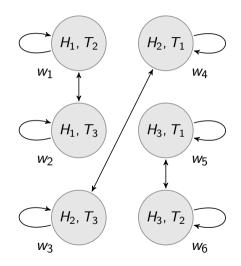
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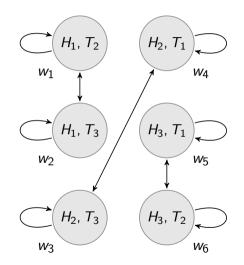
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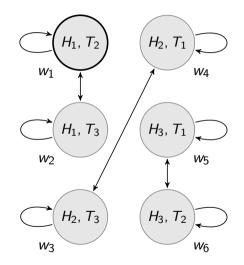
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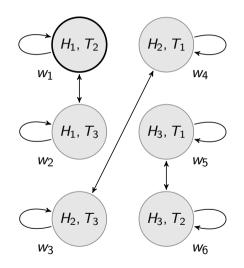
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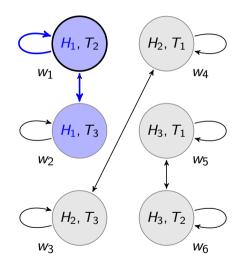
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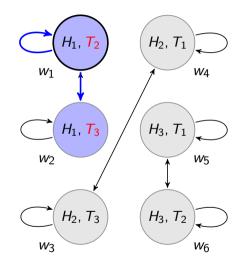
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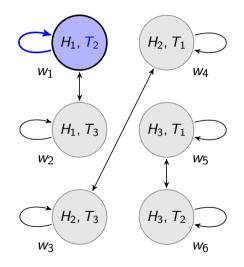
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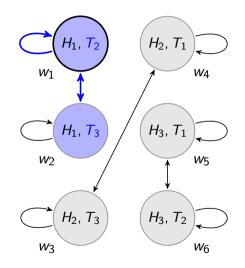
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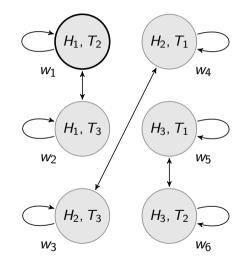
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- ► $K_a K_b \varphi$: "Ann knows that Bob knows φ "
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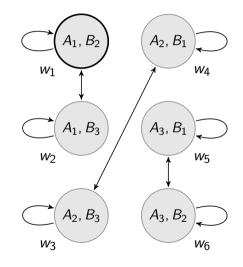
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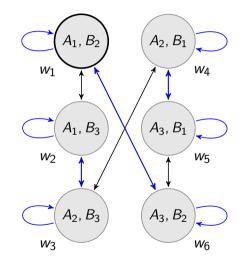
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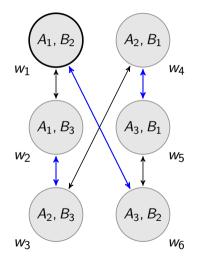
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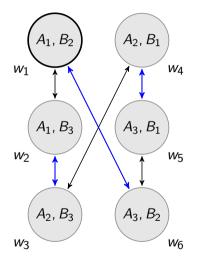
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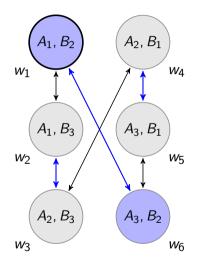


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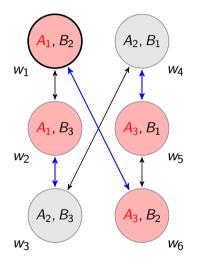


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Suppose agent c, who lives in College Park, knows that agent a lives in Amsterdam. Let r stand for 'it's raining in Amsterdam'. Although c doesn't know whether it's raining in Amsterdam, c knows that a knows whether it's raining there:

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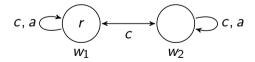
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The following picture depicts a situation in which this is true, where an arrow represents *compatibility with one's knowledge*:

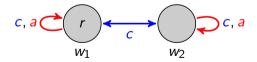


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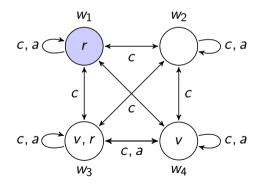


Now suppose that agent c doesn't know whether agent a has left Amsterdam for a vacation. (Let v stand for 'a has left Amsterdam on vacation'.) Agent c knows that if a is not on vacation, then a knows whether it's raining in Amsterdam; but if a is on vacation, then a won't bother to follow the weather.

$$\mathcal{K}_{c}(\neg v \to (\mathcal{K}_{a}r \lor \mathcal{K}_{a}\neg r)) \land \mathcal{K}_{c}(v \to \neg (\mathcal{K}_{a}r \lor \mathcal{K}_{a}\neg r)).$$

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 - "It is raining"
 - "The talk is at 2PM"
 - "The card on the table is a 7 of Hearts"

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- ▶ The usual definitions for \rightarrow , \lor , \leftrightarrow apply
- ► Define $L_a \varphi$ (or \hat{K}_a) as $\neg K_a \neg \varphi$

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- V : At → ℘(W) is a valuation function assigning propositional variables to worlds

Given $\varphi \in \mathcal{L}$, a Kripke model $\mathcal{M} = \langle W, (R_a)_{a \in Agt}, V \rangle$ and $w \in W$

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- wR_av if "agent a has cannot rule-out v, given her evidence and observations (at state w)"
- \blacktriangleright wR_av if "agent a is in the same local state in w and v"

 $L_a \varphi \text{ iff there is a } v \in W \text{ such that } \mathcal{M}, v \models \varphi$ I.e., $R_a(w) = \{v \mid wR_av\} \cap \llbracket \varphi \rrbracket_{\mathcal{M}} = \{v \mid \mathcal{M}, v \models \varphi\} \neq \emptyset$ $L_a \varphi \text{ iff there is a } v \in W \text{ such that } \mathcal{M}, v \models \varphi$ I.e., $R_a(w) = \{v \mid wR_av\} \cap \llbracket \varphi \rrbracket_{\mathcal{M}} = \{v \mid \mathcal{M}, v \models \varphi\} \neq \emptyset$

- ► $L_a \varphi$: "Agent *a* thinks that φ might be true."
- ► $L_a \varphi$: "Agent *a* considers φ possible."

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- H_am:///Aeent/a/Minks/Man//g/Mient/be/trueli/
- ► $L_a \varphi$: "Agent *a* considers φ possible."
- ► $L_a \varphi$: "(according to the model), φ is consistent with what a knows $(\neg K_a \neg \varphi)$ ".

Modal Formula Corresponding Property

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$\Box(arphi ightarrow \psi) ightarrow (\Box arphi ightarrow \Box \psi)$	

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$\Box(\varphi \to \psi) \to (\Box \varphi \to \Box \psi)$	
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$ eg \Box \varphi ightarrow \Box \neg \Box \varphi$	Euclidean

S5

The logic ${\bf S5}$ contains the following axioms and rules:

$$\begin{array}{ll} Pc & \text{Axiomatization of Propositional Calculus} \\ K & K(\varphi \rightarrow \psi) \rightarrow (K\varphi \rightarrow K\psi) \\ T & K\varphi \rightarrow \varphi \\ 4 & K\varphi \rightarrow KK\varphi \\ 5 & \neg K\varphi \rightarrow K \neg K\varphi \\ MP & \frac{\varphi & \varphi \rightarrow \psi}{\psi} \\ Mec & \frac{\varphi}{K\psi} \end{array}$$

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Theorem

S5 is sound and strongly complete with respect to the class of Kripke frames with equivalence relations.

Multiagent S5

The logic S5 contains the following axioms and rules:

$$\begin{array}{ll} Pc & \text{Axiomatization of Propositional Calculus} \\ K & K_i(\varphi \to \psi) \to (K_i\varphi \to K_i\psi) \\ T & K_i\varphi \to \varphi \\ 4 & K_i\varphi \to K_iK_i\varphi \\ 5 & \neg K_i\varphi \to K_i\neg K_i\varphi \\ 5 & \neg K_i\varphi \to \psi \\ \hline MP & \frac{\varphi & \varphi \to \psi}{\psi} \\ Nec & \frac{\varphi}{K_i\psi} \end{array}$$

Theorem

Multiagent **S5** is sound and strongly complete with respect to the class of Kripke frames where each relation is an equivalence relation.

Truth Axiom

 $K \phi o \phi$

Negative Introspection

$$\neg K \varphi \rightarrow K \neg K \varphi$$

▶ The agent may or may not believe φ , but has not ruled out all the $\neg \varphi$ -worlds

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- The agent has not yet entertained possibilities relevant to the truth of φ (the agent is unaware of φ).

Positive Introspection

$$K \phi
ightarrow K K \phi$$

The KK Principle

More famous is the "KK principle" (or "positive introspection"):

4 $K\varphi \rightarrow KK\varphi$.

Hintikka, one of the inventors of epistemic logic, endorsed the 4 axiom—at least for what he considered a strong notion of knowledge, found in philosophy from Aristotle to Schopenhauer.

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Hintikka rejected arguments for 4 based on claims about agents' introspective powers, or what he called "the myth of the self-illumination of certain mental activities" (67). Instead, his claim was that for a strong notion of knowledge, *knowing that one knows* "differs only in words" from *knowing* (§2.1-2.2).

Fact. In **S5**, there are only three distinct modalities (\Box , \diamondsuit , and the "empty modality")